

Kangaroo Jumping Model



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Our Design



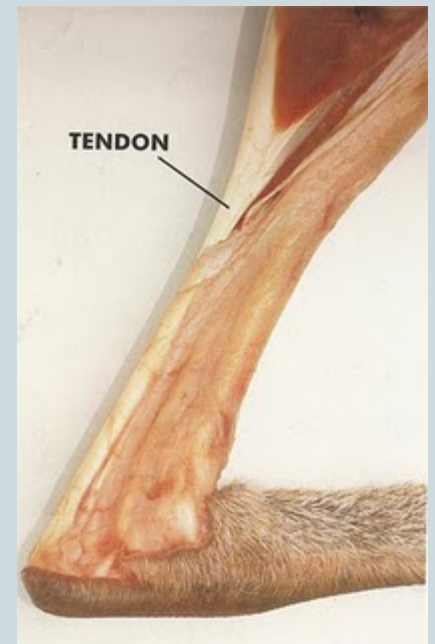
Kangaroo Jumping Model



Kangaroo Movement



- Tendons stretched when standing
- To launch, muscles pull on the leg bones and straightening them
- Tendons relax
- Kangaroo launches
- Tendons stretched again when landing
- Can jump up to 10 feet high
- Leaps on average 12 feet long



Competing Products

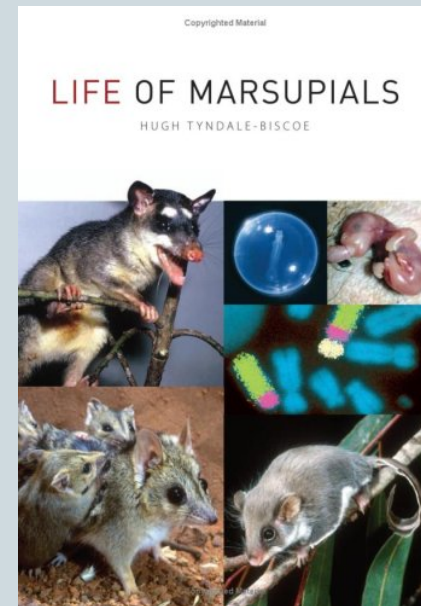


Mechanical Kangaroo: ~\$13 - \$20



Uses Gears.
Not analogous to real motion.

Books: ~\$150

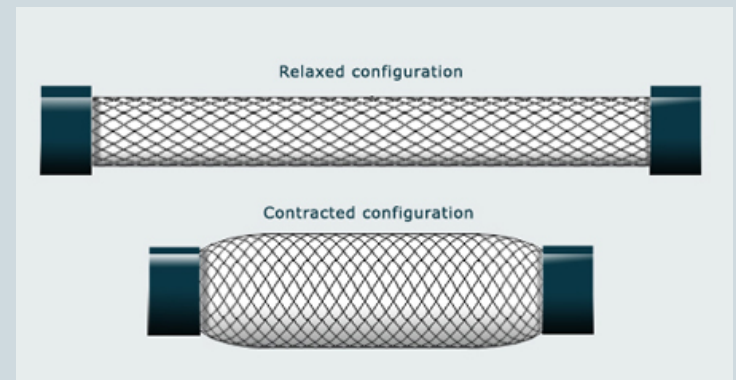


Shows
diagrams with
explanation.

Our Focus



- Purely Vertical Jumping
- Elastic Chords for Tendons
 - Different lengths and elasticity's
- Pneumatic Artificial Muscles
 - Pressurized and de-pressurized



Stakeholder Needs



• Educational Value	Teachers, Students, Admin.
• Safety	Teachers, Students
• Design	Teachers, Manufacturers
• Marketability	Investors
• Distribution	Manufacturers, Developers
• Power	Teachers
• Aesthetics	Teachers, Students
• U.I./Experience	Teachers, Students

Stakeholder Needs



- **Educational Values**
 - Must demonstrate biological system or phenomenon
 - Must hold attention of 14-17 yr olds for lesson
 - Accompanying documentation must be well-written and universally understood (multi-lingual, diagrams)
 - Must promote analytical and experimental skills
 - Must be versatile to accommodate multiple levels of students/teachers
 - Demonstrate a concept with underlying math and physics

Final Design - Educational Goals



- Model the mechanics of jumping by a kangaroo
- Show the interaction between the muscles and tendons
 - Muscles contract and pull on bones via tendons
 - Product jumps
 - Tendons stretch upon landing
- No “black box”
- Accurate depiction of leg structure



Final Design - Performance Goals

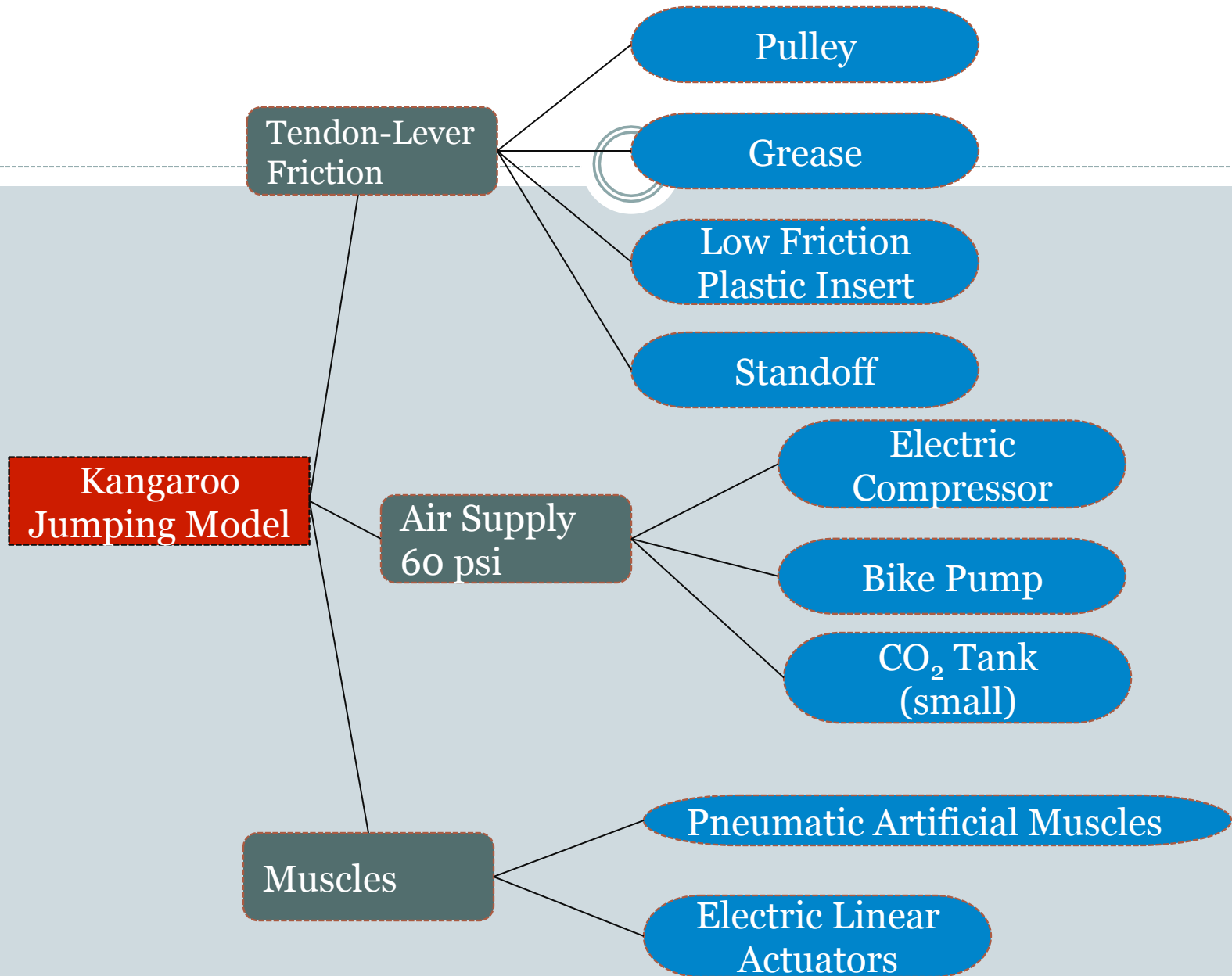


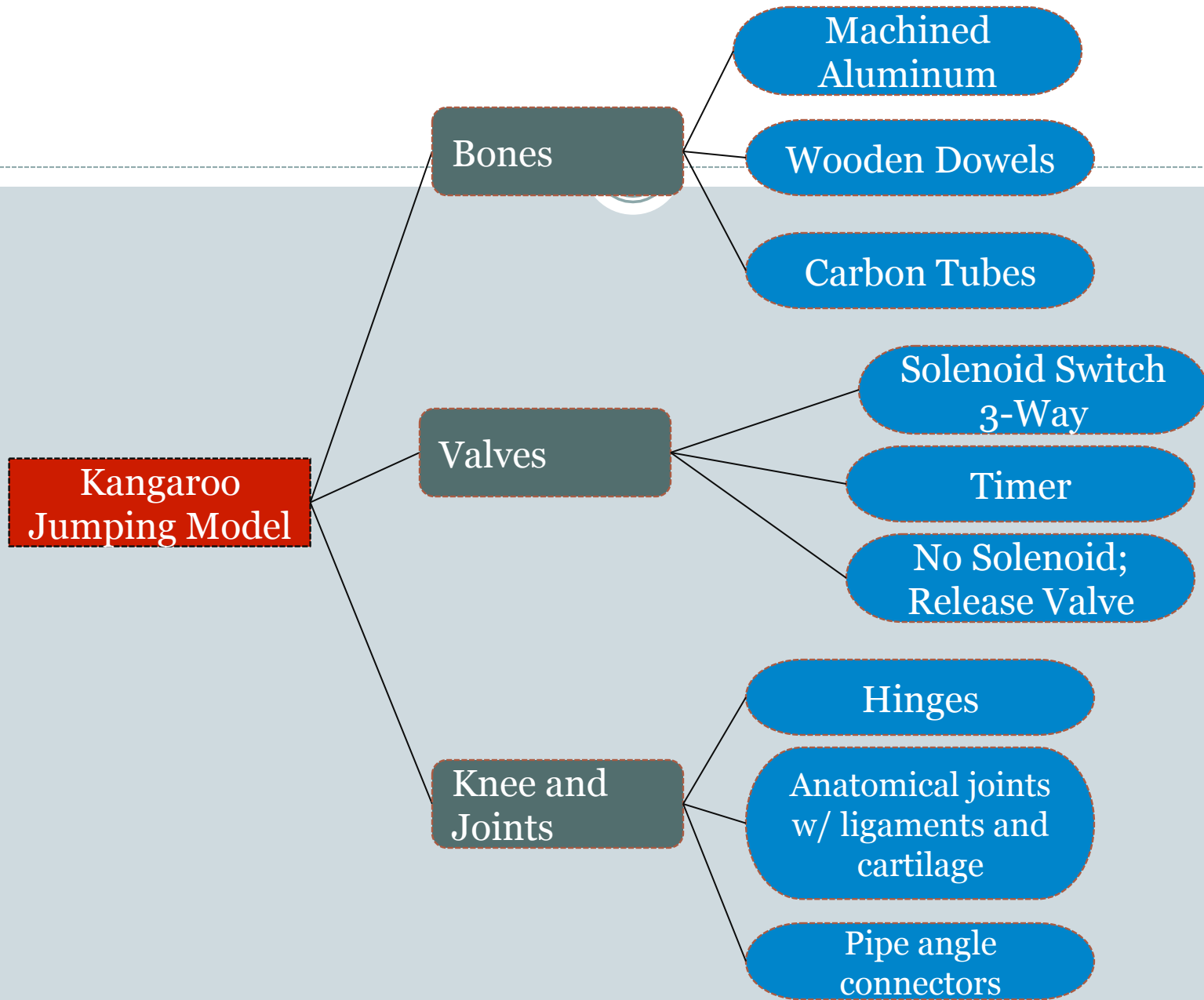
- Want the product to jump at least 6 inches
- Rebound height will be dependent on the elasticity of the bands/bungees
- Pneumatic system should be safe and easy to use while still providing over 60psi
- Students should be able to alter tendon elasticity and placement with measurable variations in jump height
- Students should be able to alter muscle strength (change the muscle) to exert different forces
- Students should be able to change the bone length for comparisons of multiple animals
- Should effectively promote the understanding of energy conservation and loss with different configurations with calculations to support
- Lightweight system should be able to be broken down and transported by the average teacher.

Critical Functionalities



Inputs	Subsystem	Function	Output
Muscle Force (Air Pressure, Electricity) Placement on Bone Muscle Actuation Duty Cycle Overall cross-sectional area of tendon elastic bundles	Muscles	Provides initial force (Compression)	Height of jump Height of subsequent jumps Understanding of tendon importance, not muscle importance on jump
	Bones	Structural part of system	
	Tendons	Stores energy for jump/converts kinetic energy for subsequent jumps	
	Air Supply	Applies air pressure to system	
	Valve	Allows muscles to hold air pressure	
	Knee + Joints	Allows movement within system while keeping system help together	
	Vertical Guide	Keeps system in line for jump	
	Tendon Connections to Bones	Applies force from tendons to bones	
	Demarketions for rulers, guide and bones	Easier to measure Height of jump	





Kangaroo Jumping Model

Muscles
connect to
Bone

Hose, circular
clamps, loose
around tube to slide

Bolts in channel

Hooks at set locations,
bungee cords to I
hooks

Demarcations
for guide and
bones

Point, laser
cured

Stickers

Vertical
Guide

Tube w/ eye
hooks or clamps

Guide wire

Guide rail w/
bushings



Main-System	Sub-Systems	Options	Comments
Kangaroo Jumping Model	Tendon-Lever Friction	A) Pulley B) Grease C) Low Friction Plastic insert D) Standoff	A) Store bought B) Dirty, maintenance required C) Manufacturing step D) Easily adjustable, no moving parts
	Air Supply 60 psi	A) Electric Compressor B) Bike Pump C) CO ₂ Tank (paintball gun)	A) \$\$, heavy B) Cheap, light C) Refillable or cheap to replace
	Muscles	A) Pneumatic Artificial Muscles B) Electric linear actuators	A) Air pressure, may avoid electricity B) Costly electronics
	Bones	A) Machined Alum B) Carbon tubes C) Wooden Dowel	A) Aesthetic, heavy, slot for muscles adjacent B) Costly, light flexible, durable C) Cheap, easy to cut, strong
	Valves	A) Push button valve B) Timer C) No solenoid, just release valve D) Switch solenoid 3-way	A) Cheap, effective B) Unnecessary unless doing constant pumping, costly C) Cheapest D) Expensive, needs electrical power

Main-System	Sub-Systems	Options	Comments
Kangaroo Jumping Model	Knee and Joints	A) Hinges B) Anatomical joints w/ ligaments and cartilage C) Pipe Angle Connectors	A) Easy, cheap, low friction B) Out of focus, not anatomy model, added complication
	Muscle connect to Bone	A) Hose, circular clamps, loose around tube to slide B) Bolts in channel C) Elastic fixed with hose clamp	A) Simple, store bought B) Not variable, more pieces, easier switching C) Easily variable
	Demarcations for rulers, guide and bones	A) Point, laser cured B) Mounted Meterstick	A) Material must be laser cutter safe B) Outsourced unless pound outline
	Vertical Guide	A) Tube w/ eye hooks or clamps B) Guide wire C) Guide rail w/ bushings	A) Rigid, allows ruling, possibly low friction B) Cheap, flexible, may allow too much oscillation

Subsystem Decisions



- Based on stakeholder needs and target specs
- Example:

Subsystem: Air Supply	Specs met (Others Don't)	Specs not met (Others Do)
Electric Compressor		-Must cost less than \$200 to develop/manufacture -Quiet Operation -Portable for teachers traveling between classrooms and schools
Bike Pump	-Must be versatile to accommodate multiple levels of students/teachers -Self or human powered	
CO2 Tank (paintball gun)		-Durable to misuse -Not to be stolen by students -Should not depend on consumables

Design of Final Product



- Subsystems

- Kangaroo Leg Model

- ✦ Bones (lightweight wood)
 - ✦ Joints
 - ✦ Ability to change mass above hip (post and weights with holes)
 - ✦ Variable positioning of tendons on bone (quick release clamps)
 - ✦ Variable tendon elasticity (larger/smaller bundles with known K)

- Pneumatic System

- ✦ Air source (bike pump - no reliance on electric)
 - ✦ Pressure tank and regulator (low cost PVC)
 - ✦ Pneumatic Muscles (can be made for <\$5 each with raw materials)
 - ✦ Push button valves for pressurization and blow-off (easy to use and learn efficient jump timing)

Critical Elements



- Muscles
- Bones & Joints
- Tendons/Tendon placement
- Pneumatic system
- Ruled vertical guide
- Lab manual



Critical Elements



- **Challenges**

- Simplifying Kangaroo leg to allow for only vertical motion
- Balancing the prototype before and after the jump
- Maintaining some biological accuracy
- Correct depiction of muscle and tendon interaction
- Creating lab experiments
- Muscle performance

- **Trade-offs**

- Restricted to only vertical movement
- Limited depiction of muscles in the leg
- Overall ability to jump high

Concerns



- **Performance**
 - Not enough force to jump
 - Friction on vertical guide
 - Part durability
 - Air pressure regulation
 - Joint and tendon friction
 - Force absorption due to bending bones or non-rigid structure
- **Educational**
 - Effectiveness of energy conservation concepts
 - Biological inspiration
- **Design must meet needs and target specs**



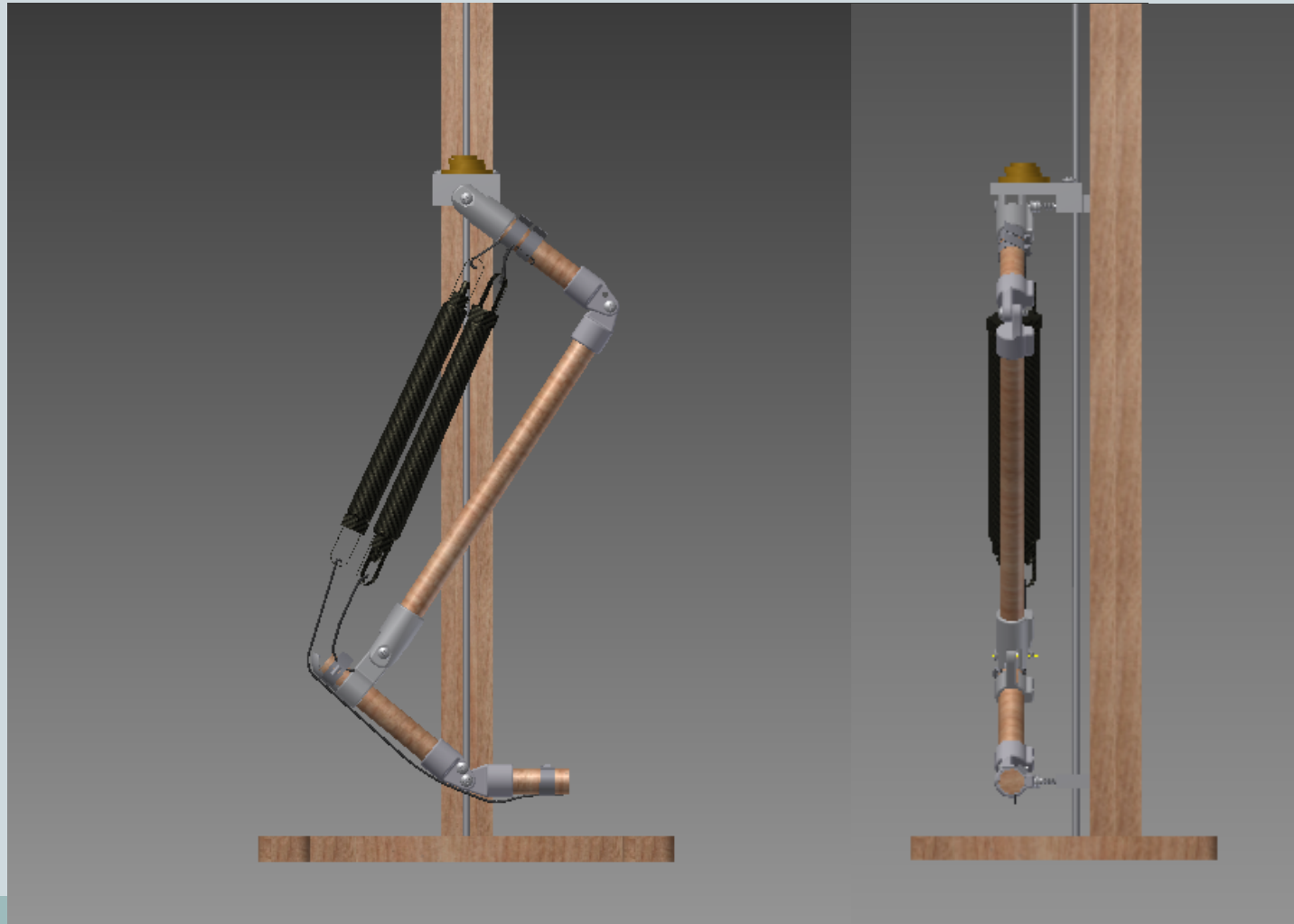
We Pay For Performance!

Prototype - Performance Goals



- Prototype should jump at least 3 inches high
- Rebound height will be dependent on the elasticity of the bands/bungees
- Pneumatic system should be safe and easy to use while still providing over 60psi
- Students should be able to alter tendon elasticity and placement with measurable variations in jump height
- Should effectively promote the understanding of energy conservation and loss with different configurations

Detailed Design of Prototype



How it Works



The important muscles of the lower leg used by kangaroos in jumping are the calf muscles, gastrocnemius and plantaris. The first of these is the larger and the main agent responsible for extending the foot and so lifting the body off the ground. It begins on the underside of the femur (or thigh bone) and swells into two large muscle masses, which then narrow at the ankle into a powerful tendon that is attached to the heel. The second smaller plantaris muscle is also attached to the thigh bone but its tendon passes round the heel and attaches to the sole of the foot, especially to the large 4th digit, the great toe of the kangaroo with which it drives off from the ground (Fig. 9.11). At the end of a stride, while the kangaroo is in the air, the two hind feet are fully extended forward; then as the feet strike the ground they are quickly flexed, so that the two muscles and their tendons are stretched to their full extent. The muscles themselves change only slightly in length, because the muscle fibres are arranged in a pennate manner, but in a large kangaroo the 200 mm long tendons are stretched by 11 mm. The elastic energy stored in the stretched tendons is rapidly released in the next jump as the tendons shorten.

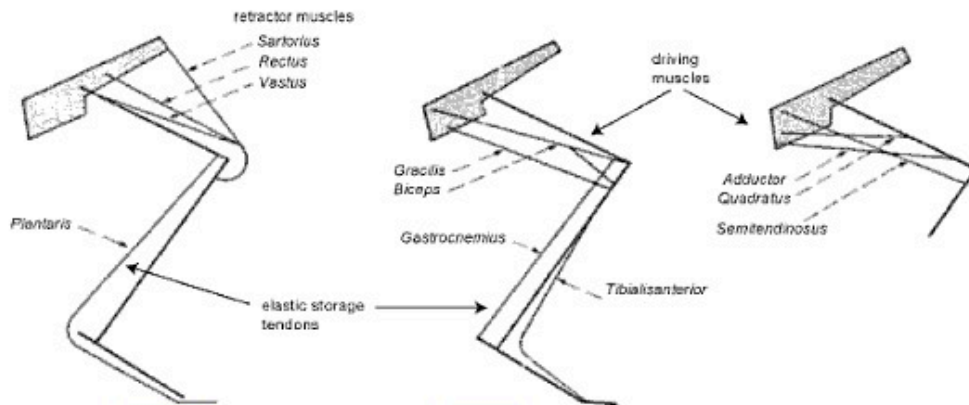


Figure 9.11: Diagram of the hind limb of a kangaroo to show the disposition of the main muscles involved in hopping: the muscles that deliver the main driving force and those involved in retraction are grouped around the hip, while the muscles of the lower limb store the elastic energy when the kangaroo first lands at the end of a hop. After Alexander and Vernon (1975).

JUMPING

Gastrocnemius

- Larger of the two main jumping muscles.
- Connects femur (thigh) to heel via tendon

Plantaris

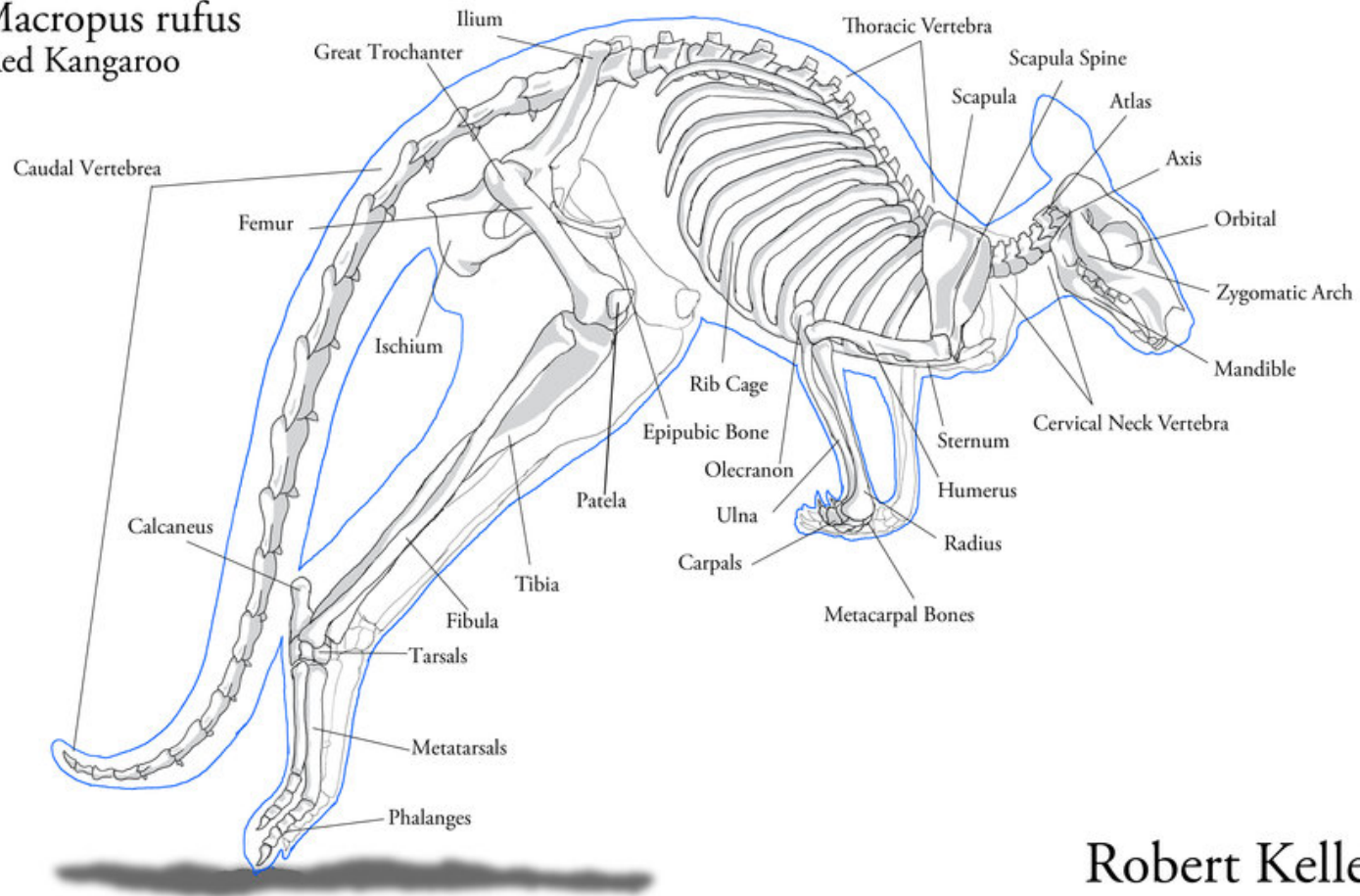
- Connects femur to large toe
- Wraps around heel of foot and connects at the sole via tendon

Landing stretches tendons and stores energy for next bound

How it Works



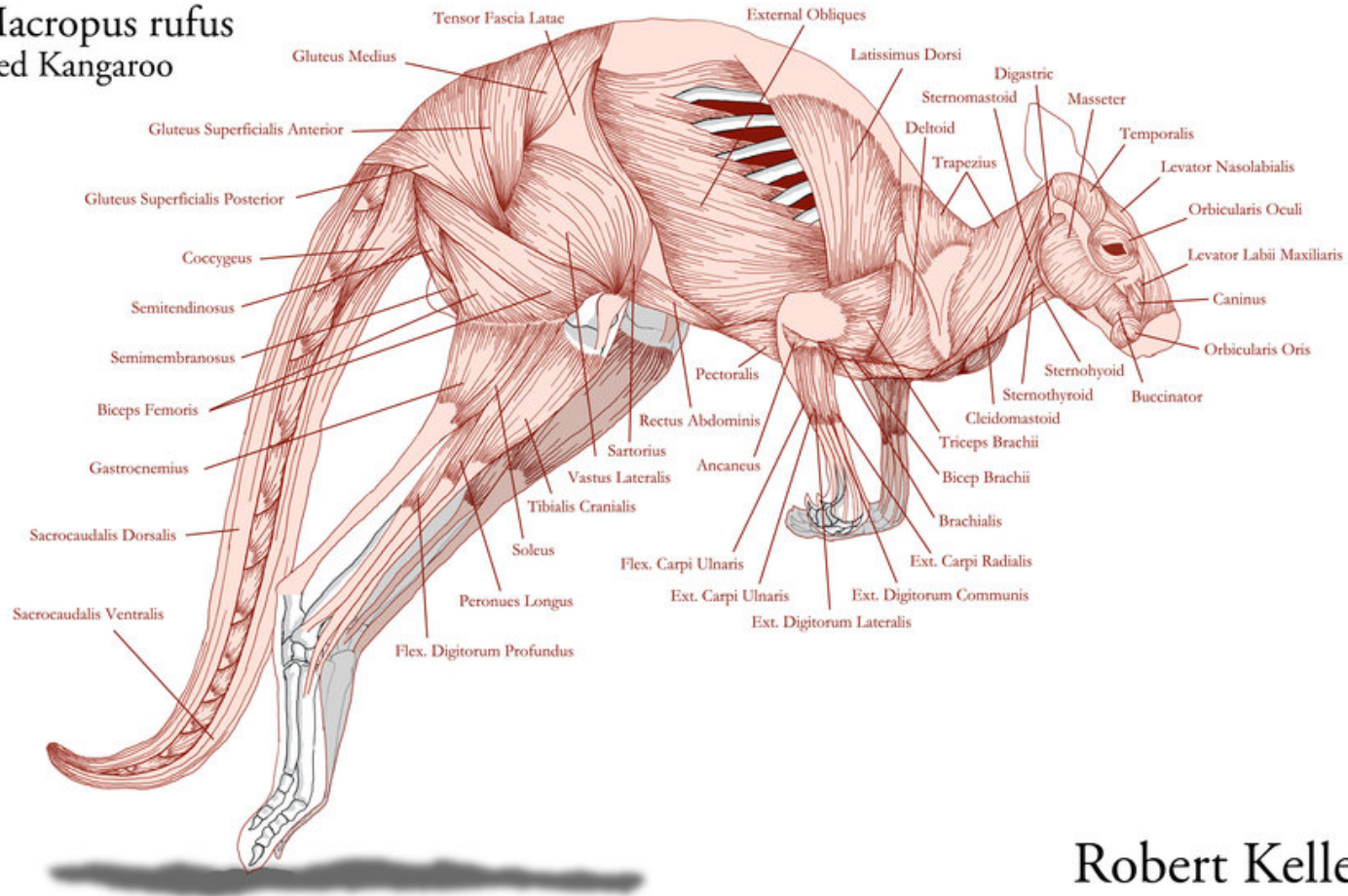
Macropus rufus
Red Kangaroo



Robert Kelley

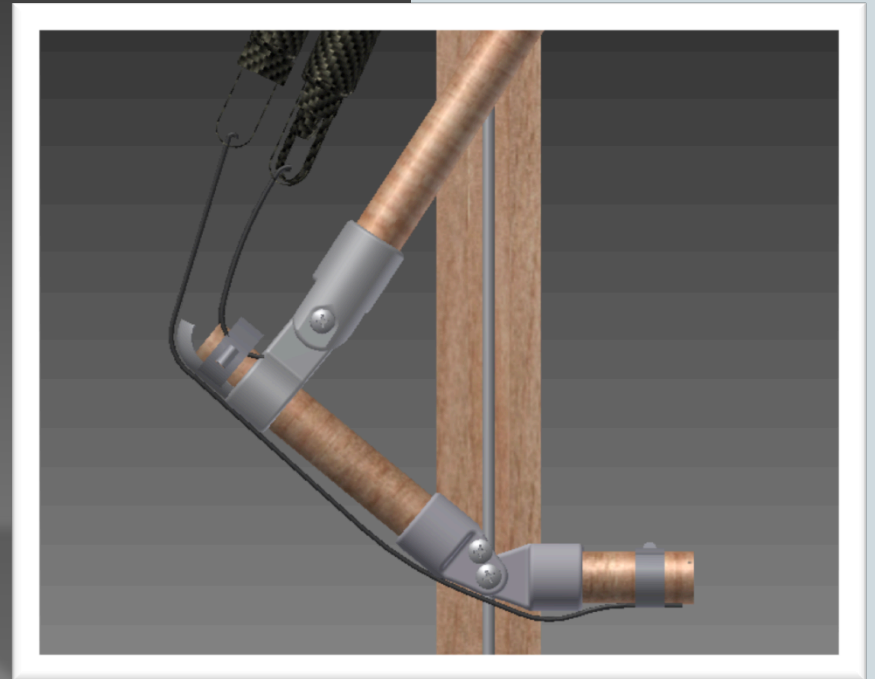
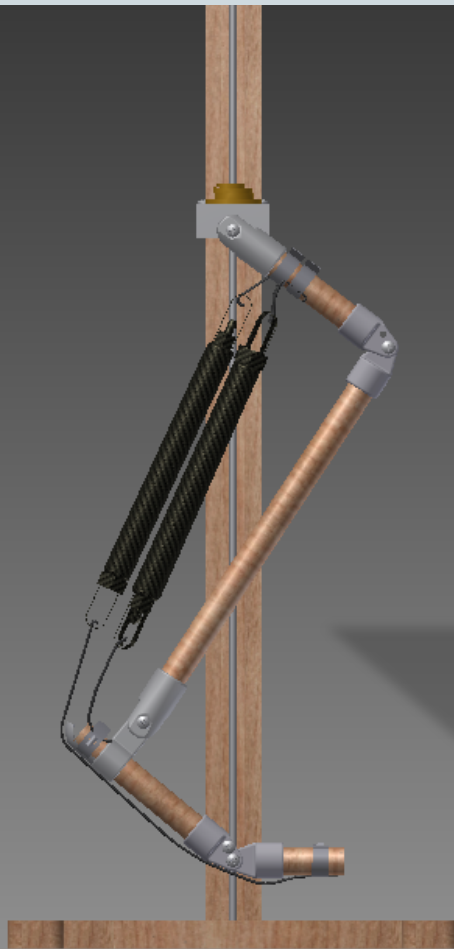
How it Works

Macropus rufus Red Kangaroo



Robert Kelley

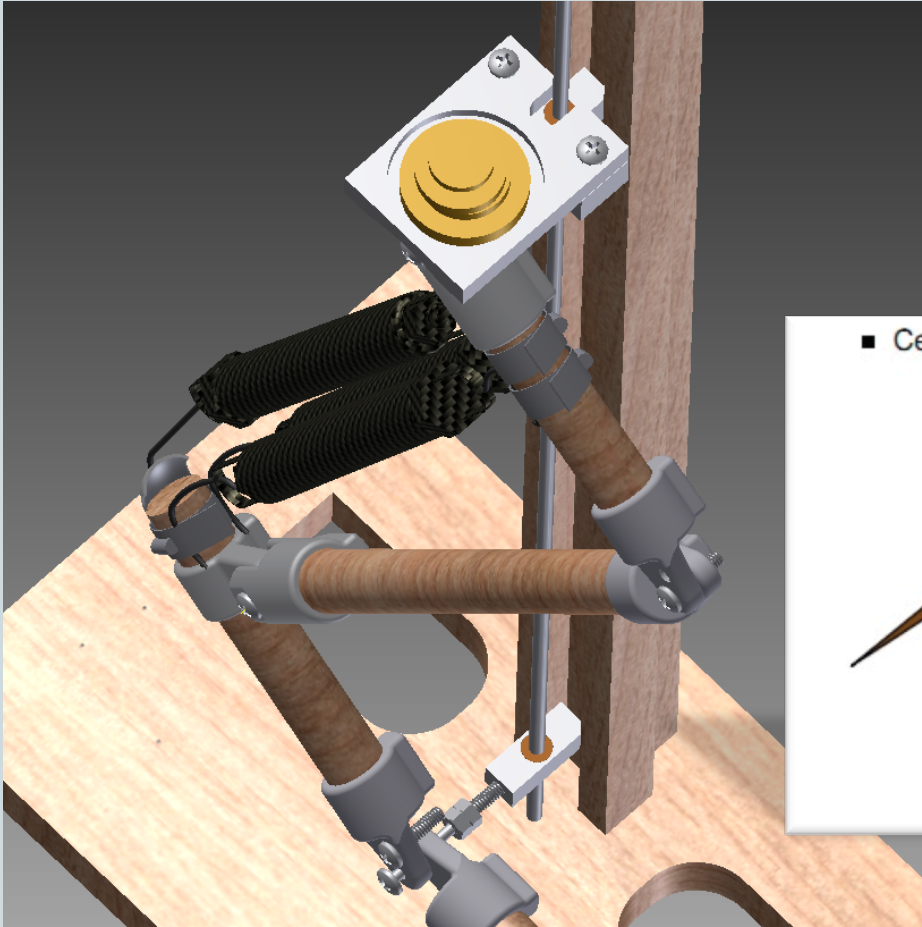
How it Works



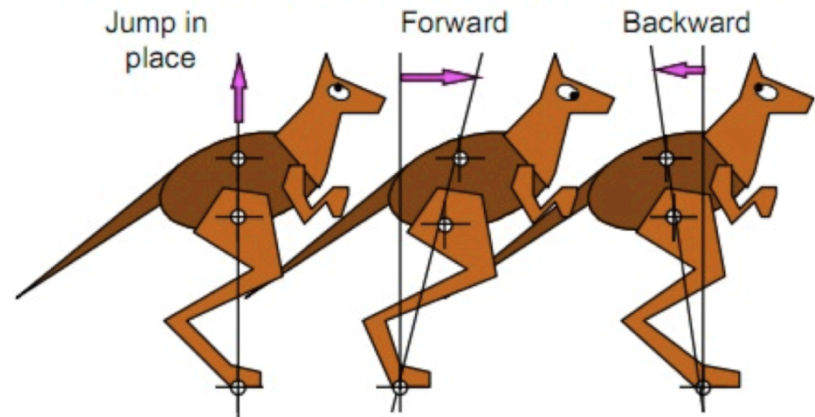
How it Works



Bushings keep the center of mass (mass is variable), hip and toe joint aligned vertically

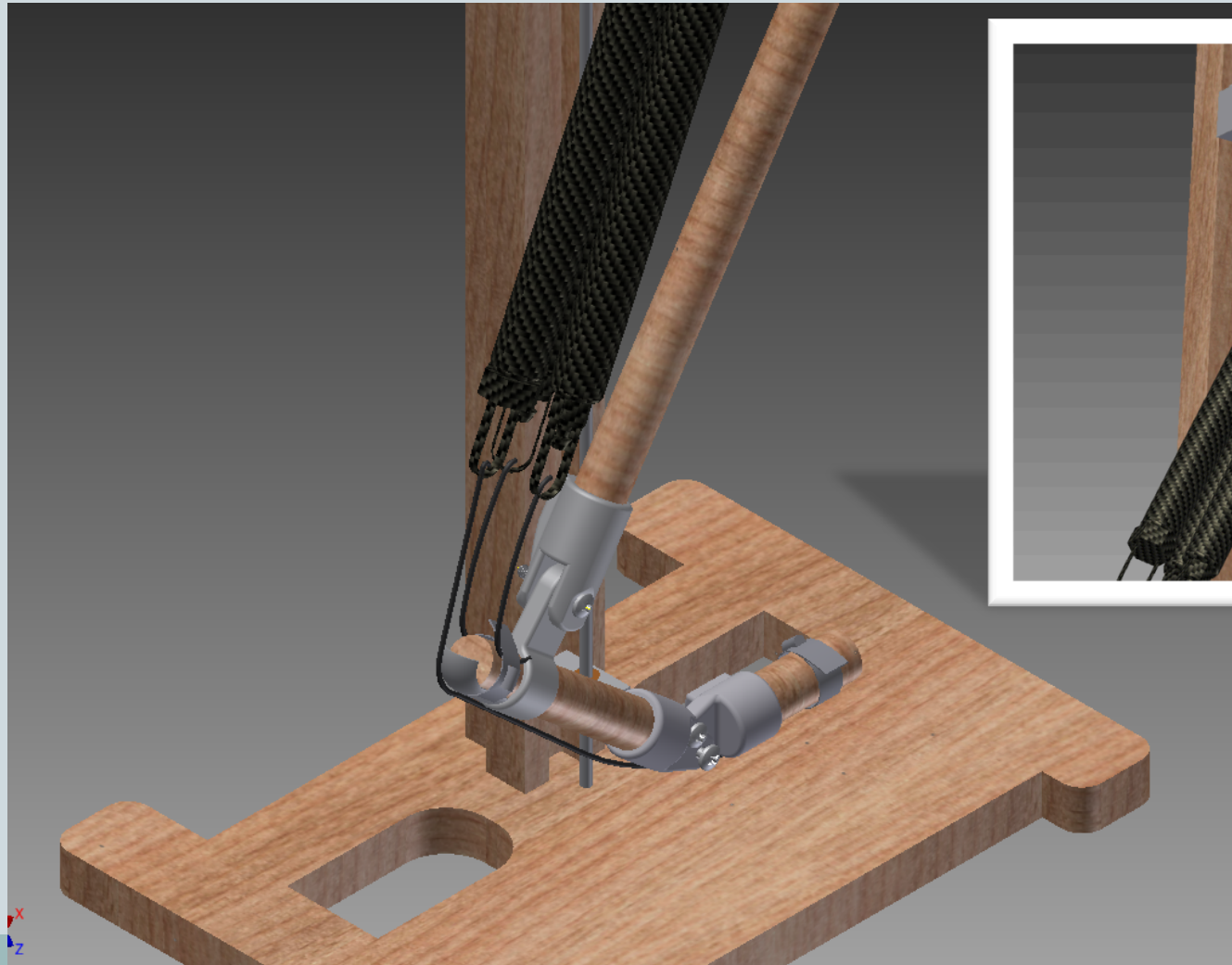


- Center of gravity, hip and toe always on the same line



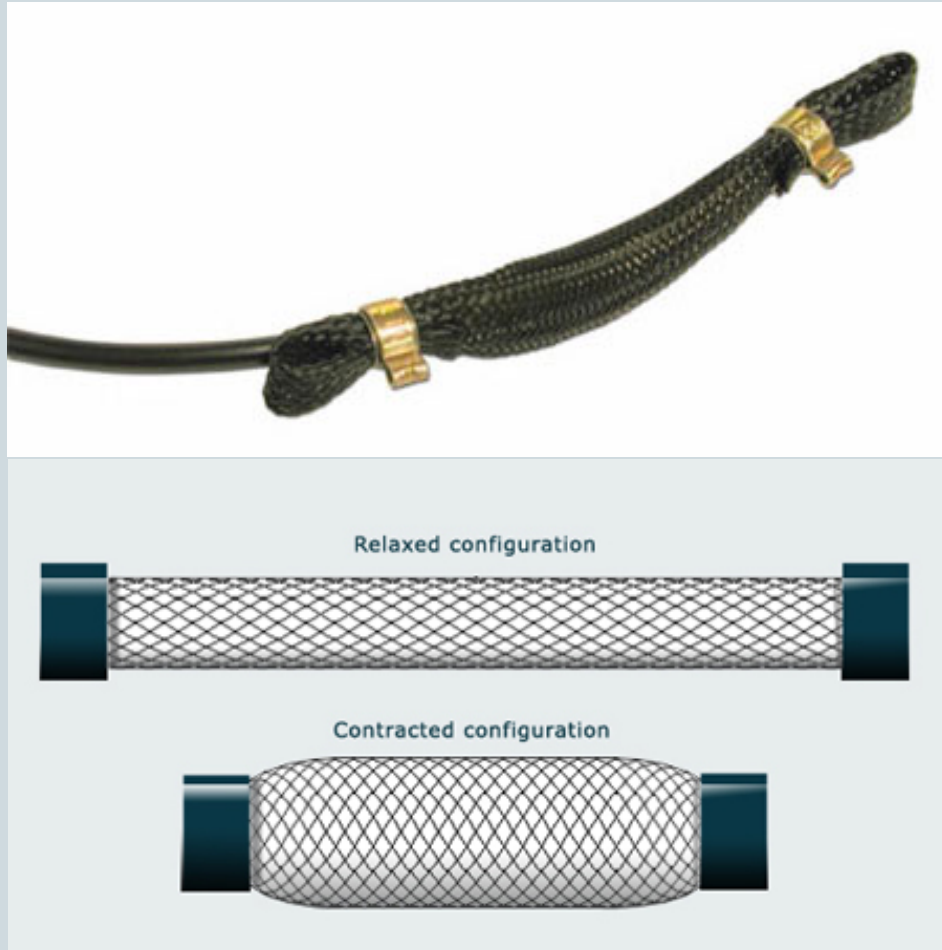
Umberto Costanzini & Young Cho

How it Works



Entire
structure is
12" x 16" x 48"

How it Works

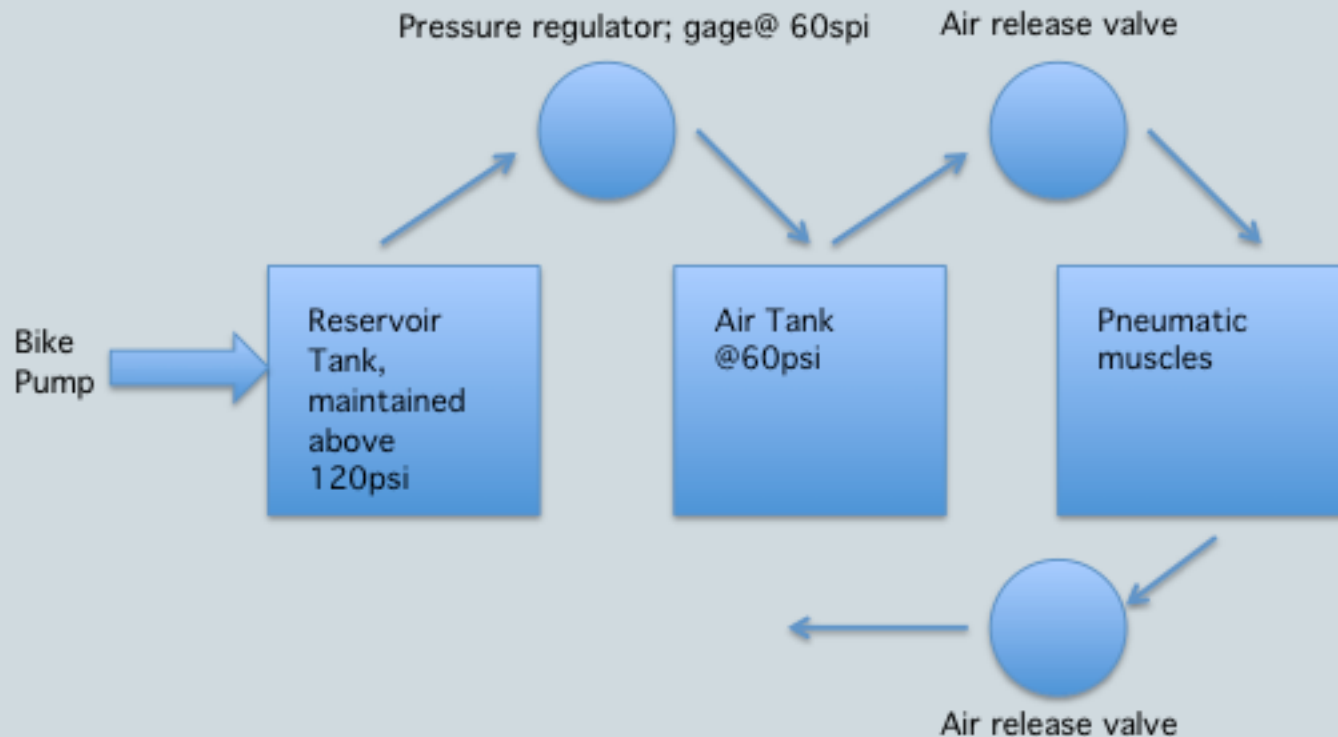


McKibben Muscles

- Pressurized to above 60psi
- Can lift about 6lbs by 1.5" (8" muscle)
- Pressure swells inner bladder, causing cross sectional area to increase. This nylon mesh (think Chinese finger trap) shrinks in length as its diameter expands.

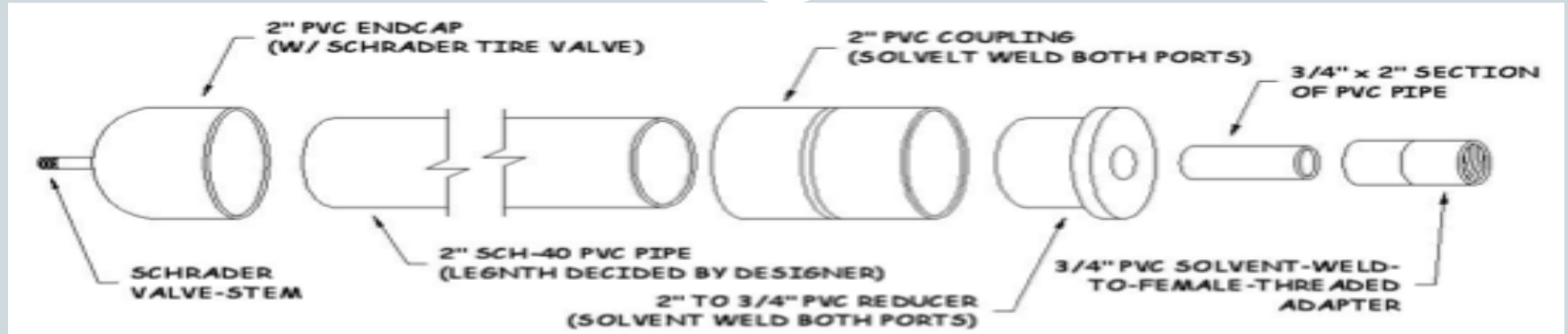
Manufacturing and Part Acquisition

Compressed Air System



Schematic Diagram of compressed air system

Manufacturing and Part Acquisition



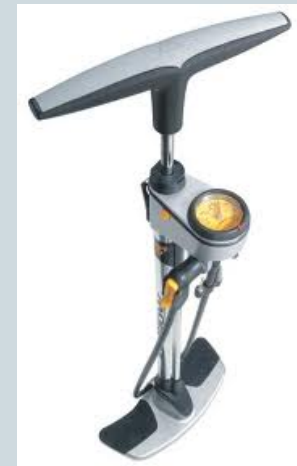
Design concept for Reservoir Tanks



Pressure Regulator with gage



Push button valve



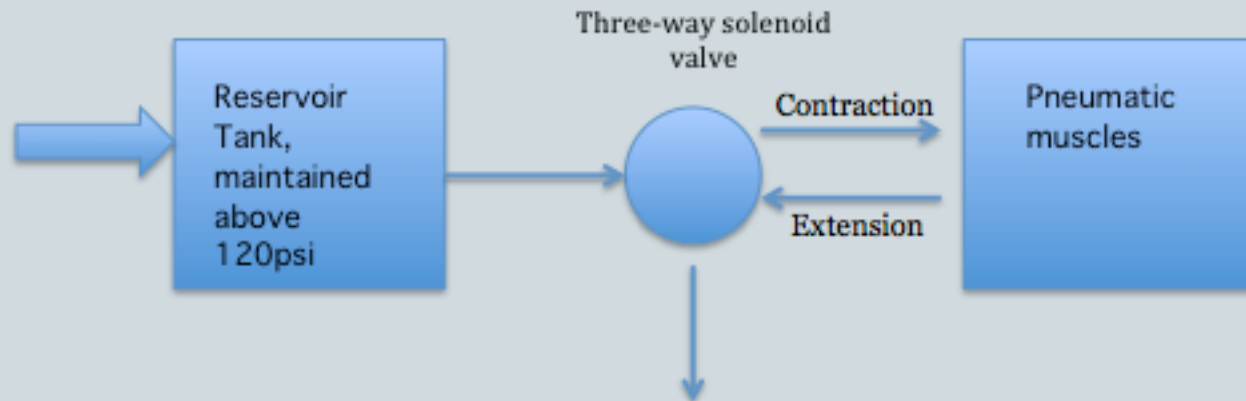
Bike pump with gage

Detailed Design of Prototype



- **Air System Components**

- Two tank air reservoir
- Three way solenoid air control valve
- Electricity powered



Manufacturing and Part Acquisition



- Almost all parts are standard from McMaster-Carr
- Pneumatic Muscles can be made from silicon tubing, nylon wire conduit, crimp clamps (or wire) and appropriate valves
- Majority of Air System components already owned



Parts List [McMaster-Carr]

Part Number/ASIN	Description	Form	Shipping Time	Qty	Unit Price (\$)	Cost (\$)
4698T82	Aluminum Slip-on Rail Fittings Adjustable-Angle Elbow, Fits 3/4" Pipe Size	each	next day	2	12.01	24.02
4698T96	Aluminum Slip-on Rail Fittings Adjustable-Angle Tee, Fits 3/4" Pipe Size	each	next day	2	11.24	22.48
9683K21	1"x36" Birch Dowel	pack of 2	next day	1	9.71	9.71
1031K68	Precision Ceramic-Coated Aluminum Shaft 1/4" Diameter, 48" Length	each	within 2 weeks	1	24.48	24.48
9440T13	1/4" Flange Bearing	each	next day	4	0.99	3.96
5362K13	Worm-Drive Hose & Tube Clamp with Thumb Screw	pack of 5	next day	1	7.73	7.73
8858T82	1/8" RED Latex Rubber with Polypropylene Cover			50	0.11	5.5
8975K417	3"x12"x3/4" Aluminum Stock	each	next day	1	20.15	20.15
5486K112	M6x1x22 Hex-Head Bolt	individual	next day	2	6.71	13.42
5111K667	Aluminum (6061) 5mm OD Rod	individual	next day	2	4.43	8.86
5392K11	1/4" rigid white polypropylene tubing	form of 25 ft	next day	1	10.5	10.5

Parts List [Miscellaneous]



- 1/4-20 phillips-head machine screws
 - 1" 1.5" 2.75"
- 1/4-20 bolts
- About 300in² of 1" thick birch

These parts can be bought from Home Depot in quantities necessary

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